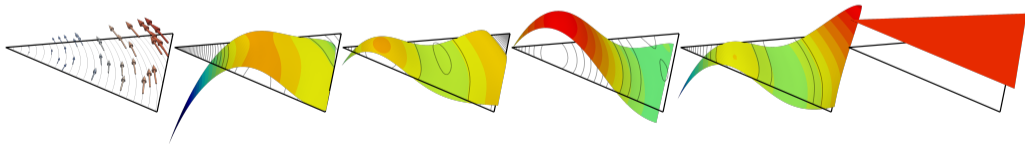


Embedded Trefftz discontinuous Galerkin methods

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Trefftz-DG methods

$$\begin{cases} \mathcal{L}u = 0 \text{ in } \Omega, \\ + \text{ bndc. on } \partial\Omega, \end{cases}$$

Find $u_h \in \mathbb{T}^p(\mathcal{T}_h)$, s.t. $a_h^{\text{DG}}(u_h, v_h) = \ell_h^{\text{DG}}(v_h) \quad \forall v_h \in \mathbb{T}^p(\mathcal{T}_h)$ with

$$\mathbb{T}^p(\mathcal{T}_h) := \Pi_{K \in \mathcal{T}_h} \mathbb{T}^p(K), \quad \mathbb{T}^p(K) := \{v_h \in \mathbb{P}^p(K) \text{ s.t. } \mathcal{L}u = 0 \text{ on } K\}$$

$$\dim \mathbb{T}^p(\mathcal{T}_h) = \mathcal{O}(p^{n-1}) \ll \dim \mathbb{P}^p(\mathcal{T}_h) = \mathcal{O}(p^n)$$

Assumption: Trefftz space is 'rich enough' ($\mathcal{L} = \sum_{l=1}^d \alpha_l \partial_{x_l}^{\beta_l}$ for $\alpha_l \in \mathbb{R}$ and $\beta_l \in \mathbb{N}$)

Example: Laplace equation

$$\mathcal{L}u = -\Delta u = 0 \text{ in } \Omega, \quad u = g \text{ on } \partial\Omega.$$

$$\mathbb{T}^p(K) = \{1, x, y, xy, x^2 - y^2, x^3 - 3xy^2, \dots\}$$

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$$\begin{aligned} a_h(u, v) &= \sum_K \int_K \nabla u \nabla v \, dx + \sum_{F \in \mathcal{F}_h^{\text{int}}} \int_F \overbrace{-\{\{\partial_{\mathbf{n}} u\}\}[v]}^{\text{consistency}} \overbrace{-\{\{\partial_{\mathbf{n}} v\}\}[u]}^{\text{symmetry}} \overbrace{+ \alpha p^2 h^{-1} [u][v]}^{\text{stability}} \, ds \\ &\quad + \sum_{F \in \mathcal{F}_h^{\text{bnd}}} \int_F -\partial_{\mathbf{n}} u \, v - \partial_{\mathbf{n}} v \, u + \alpha p^2 h^{-1} uv \, ds \\ \ell(v) &= \sum_{F \in \mathcal{F}_h^{\text{bnd}}} \int_F (-\partial_{\mathbf{n}} v + \alpha p^2 h^{-1} v) g \, ds. \end{aligned}$$

$\{\{\cdot\}\}$: average across facets, $[\cdot]$: jump across facets. \rightsquigarrow communication between neighbors.

Embedded Trefftz-DG method

- ▶ Goal: Represent **Trefftz basis** $\{\psi_j\}_M$ in the **standard DG basis** $\{\phi_i\}_N$:

$$\psi_j = \sum_{i=1}^N \mathbf{T}_{ij} \phi_i, \quad j = 1, \dots, M, \quad \text{for } \mathbf{T} \in \mathbb{R}^{N \times M}.$$

Then instead of solving $\mathbf{A} \mathbf{u}_P = \mathbf{b}$ we solve $\mathbf{T}^T \mathbf{A} \mathbf{T} \mathbf{u}_T = \mathbf{T}^T \mathbf{b}$.

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- ▶ Recipe:

$$\mathbf{T} = \ker(\mathbf{W}) \quad \text{with} \quad \mathbf{W} = \sum_{K \in \mathcal{T}_h} \langle \mathcal{L} \phi_i, \mathcal{L} \phi_j \rangle_K$$

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- ▶ Benefit: $\mathbf{T}^T \mathbf{A} \mathbf{T} \in \mathbb{R}^{M \times M}$ with

$$\dim \mathbb{T}^p(\mathcal{T}_h) = M \ll N = \dim \mathbb{P}^p(\mathcal{T}_h)$$

Embedded Trefftz-DG method

$$\mathbf{T} = \ker(\mathbf{W}) \text{ with } \mathbf{W} = \sum_{K \in \mathcal{T}_h} \langle \mathcal{L}\phi_i, \mathcal{L}\phi_j \rangle_K$$

On each mesh element use SVD (or QR)

$$\mathbf{W}|_K = \begin{pmatrix} | & & | & & | & & | \\ \mathbf{u}_1 & \dots & \mathbf{u}_L & \mathbf{u}_{L+1} & \dots & \mathbf{u}_N \\ | & & | & & | & & | \end{pmatrix} \cdot \begin{pmatrix} \sigma_1 & & & & & & \\ & \dots & & & & & \\ & & \sigma_L & & & & \\ & & & 0 & & & \\ & & & & \dots & & \\ & & & & & 0 & \end{pmatrix} \cdot \begin{pmatrix} \text{---} & \mathbf{v}_1^T & \text{---} \\ & \vdots & \\ \text{---} & \mathbf{v}_L^T & \text{---} \\ \text{---} & \mathbf{v}_{L+1}^T & \text{---} \\ & \vdots & \\ \text{---} & \mathbf{v}_N^T & \text{---} \end{pmatrix}$$

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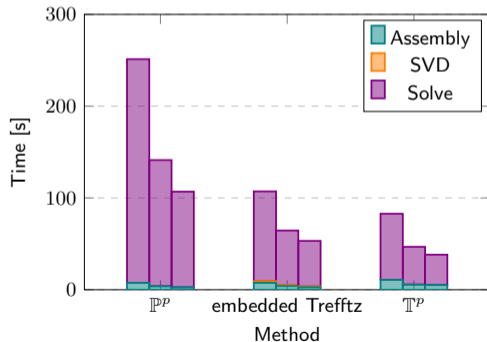
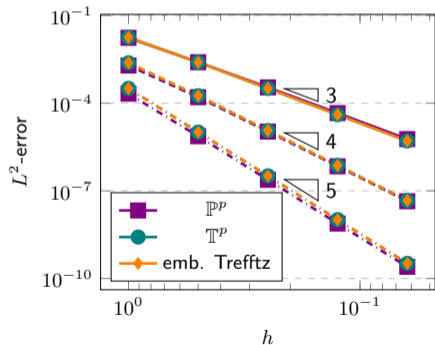
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Lemma (Conditioning of the embedded Trefftz method)

$$\kappa_2(\mathbf{T}^T \mathbf{A} \mathbf{T}) \leq \kappa_2(\mathbf{A}).$$

Example: Laplace equation II

$$\begin{cases} -\Delta u = 0 & \text{in } \Omega, \\ u = g & \text{on } \partial\Omega. \end{cases}$$



Benefits of Embedded Trefftz DG

So far:

Embedded Trefftz DG ...

1. ... facilitates implementation of existing **polynomial** Trefftz methods
2. ... is computationally (a bit) more expensive than "direct" Trefftz spaces
3. ... inherits **conditioning** properties from DG scheme

Next up:

Can we deal with ...

1. ... PDEs where no (suitable) polynomial Trefftz spaces exists?
2. ... inhomogeneous PDEs?

Embedded Trefftz - no polynomial Trefftz space

$$\begin{cases} \mathcal{L}u = -\Delta u - \omega^2 u = 0 & \text{in } \Omega, \\ \frac{\partial u}{\partial n_{\mathbf{x}}} + iu = g & \text{on } \partial\Omega. \end{cases}$$

Trefftz space given by plane waves

$$\{e^{-i\omega(d_j \cdot \mathbf{x})} \text{ with } j = -p, \dots, p\} \not\subset \mathbb{P}^p(\mathcal{T}_h).$$

Embedded Trefftz - no polynomial Trefftz space

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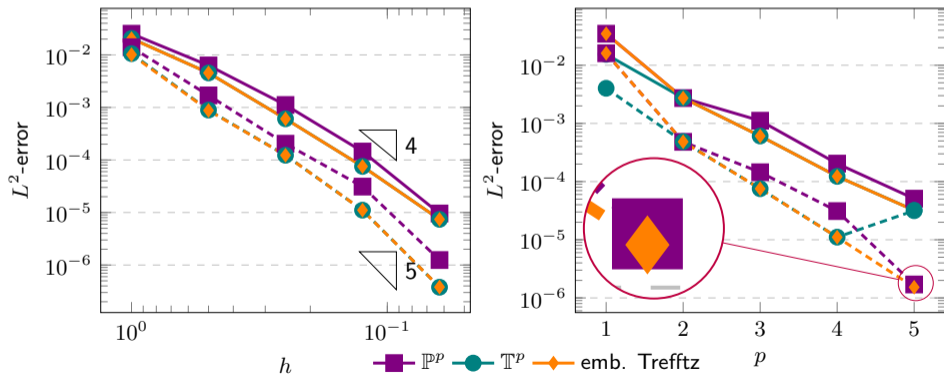
Introduce a *weak Trefftz space* for the embedding

$$\mathbb{T}^p(\mathcal{T}_h) = \{v \in \mathbb{P}^p(\mathcal{T}_h), \Pi \mathcal{L}v = 0 \text{ on each } K \in \mathcal{T}_h\}.$$

$$\mathbf{T} = \ker(\mathbf{W}) \text{ with } \mathbf{W} = \sum_{K \in \mathcal{T}_h} \langle \mathcal{L}\phi_i, \psi_j \rangle_K, \quad \forall \psi_j \in \mathbb{P}^{p-2}$$

Example: Helmholtz

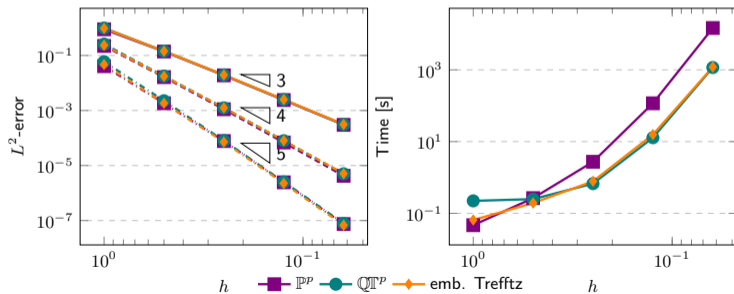
$$\begin{cases} -\Delta u - \omega^2 u = 0 & \text{in } \Omega, \\ \frac{\partial u}{\partial n_{\mathbf{x}}} + iu = g & \text{on } \partial\Omega. \end{cases}$$



Example: Acoustic wave equation

$$\begin{cases} \nabla \cdot \boldsymbol{\sigma} + c(\mathbf{x})^{-2} \frac{\partial v}{\partial t} = 0 & \text{in } \Omega \times [0, T], \\ \nabla v + \frac{\partial \boldsymbol{\sigma}}{\partial t} = \mathbf{0} & \text{in } \Omega \times [0, T], \\ v(\cdot, 0) = v_0, \boldsymbol{\sigma}(\cdot, 0) = \boldsymbol{\sigma}_0 & \text{on } \Omega \times \{0\}, \\ v = g_D & \text{on } \partial\Omega \times [0, T], \end{cases}$$

With $c(x, y) = 1 + x + y$



Embedded Trefftz - inhomogeneous problem

$$\begin{cases} \mathcal{L}u = f \text{ in } \Omega, \\ + \text{ bndc. on } \partial\Omega, \end{cases}$$

On each element we can construct a particular solution using the pseudo-inverse

$$\mathbf{W}^\dagger = \begin{pmatrix} | & & | & & | & & | \\ \mathbf{v}_1 & \dots & \mathbf{v}_L & \mathbf{v}_{L+1} & \dots & \mathbf{v}_N & \\ | & & | & & | & & | \end{pmatrix} \cdot \begin{pmatrix} \frac{1}{\sigma_1} & & & & & & \\ & \ddots & & & & & \\ & & \frac{1}{\sigma_L} & & & & \\ & & & 0 & & & \\ & & & & \ddots & & \\ & & & & & 0 & \end{pmatrix} \cdot \begin{pmatrix} \text{---} & \mathbf{u}_1^T & \text{---} \\ \text{---} & \vdots & \text{---} \\ \text{---} & \mathbf{u}_L^T & \text{---} \\ \text{---} & \mathbf{u}_{L+1}^T & \text{---} \\ \text{---} & \vdots & \text{---} \\ \text{---} & \mathbf{u}_N^T & \text{---} \end{pmatrix}$$

For $u_{h,f}$ a particular solution, we are looking for a solution $u_{\mathbb{T}} \in \mathbb{T}^p(\mathcal{T}_h)$ that (uniquely) solves

$$a_h(u_{\mathbb{T}}, v_{\mathbb{T}}) = \ell(v_{\mathbb{T}}) - a_h(u_{h,f}, v_{\mathbb{T}}) \quad \forall v_{\mathbb{T}} \in \mathbb{T}^p(\mathcal{T}_h).$$

Example: Poisson

$$\begin{cases} \Delta u = f & \text{in } \Omega, \\ u = g_D & \text{on } \partial\Omega \end{cases}$$

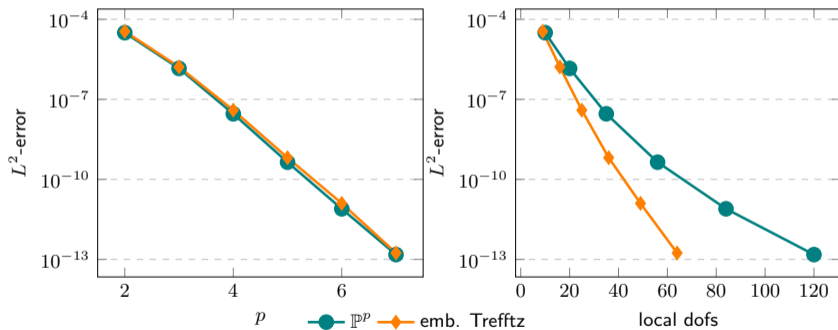


Figure: Numerical results for Poisson equation, 3D, mesh size $h = 0.25$.

Example code

Require: Basis functions $\{\phi_i\}_i$, DG formulation (a_h, l) , operators $\mathcal{L}, \tilde{\mathcal{L}}$, truncation parameter ε , r.h.s. f

```
1: function DG MATRIX
2:    $(\mathbf{A})_{ij} = a_h(\phi_j, \phi_i)$ 
3:    $(\mathbf{l})_i = l(\phi_i)$ 
4: for  $K \in \mathcal{T}_h$  do
5:    $(\mathbf{W}_K)_{ij} = \langle \mathcal{L}\phi_j, \tilde{\mathcal{L}}\phi_i \rangle_{0,h}$ 
6:    $\mathbf{T}_K = \ker_h(\varepsilon; \mathbf{W}_K)$ 
7:   if  $f \neq 0$  then
8:      $(\mathbf{w}_K)_i = \langle f, \tilde{\mathcal{L}}\phi_i \rangle_{0,h}$ 
9:      $(\mathbf{u}_f)_K = \mathbf{W}_K^\dagger \mathbf{w}_K$ 
10: Solve  $\mathbf{T}^T \mathbf{A} \mathbf{T} \mathbf{u}_\mathbb{T} = \mathbf{T}^T (\mathbf{l} - \mathbf{A} \mathbf{u}_f)$ 
11:  $\mathbf{u}_h = \mathbf{T} \mathbf{u}_\mathbb{T} + \mathbf{u}_f$ 
12: output  $\mathbf{u}_h$ 
```

```
1 def Solve(mesh, order, dgscheme,
2           L, Ltilde, eps,
3           rhs):
4     fes = L2(mesh, order=order, dgjumps=True)
5     uh = GridFunction(fes)
6     a, f = dgscheme(fes)
7     u, v = fes.TnT()
8     W = L(u)*Ltilde(v)*dx
9     w = rhs*Ltilde(v)*dx
10    T, uf = TrefftzEmbedding(W, fes, eps, w)
11    Tt = T.CreateTranspose()
12    TA = Tt@a.mat@T
13    ut = TA.Inverse()*(Tt*(f.vec-a.mat*uf))
14    uh.vec.data = T*ut + uf
15    return uh
```

Conclusion

Summary

- ▶ reduce test/trial-spaces using a projection that infers structural properties
- ▶ construct an embedding of Trefftz (like) subspaces in a very generic way
- ▶ works for inhomogeneous PDEs and non-constant coefficients

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